

A tribological model for chocolate in the mouth: General implications for slurry-lubricated hard/soft sliding counterfaces

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We have investigated the rheological and lubrication properties of molten chocolate samples. To this end, a series of chocolate samples having various textural/compositional features have been prepared. The rheological properties of the chocolate samples are discussed in terms of the Casson model. The lubrication properties of the molten chocolate samples have been characterized by means of pin-on-disk tribometry. For the tribo-pairs, zirconia (ZrO_2) and poly(tetrafluoroethylene) (PTFE) have been used in all permutations for both slider (pin) and track (disk), providing the four tribo-pair combinations; $\text{ZrO}_2/\text{ZrO}_2$, PTFE/ ZrO_2 , ZrO_2/PTFE , and PTFE/PTFE. The results showed that both the rheological and lubrication properties of the chocolate samples are strongly influenced by the textural and compositional characteristics. The lubrication properties are further influenced by the choice of the tribo-pair. The different lubrication properties of the chocolate samples at different tribo-pairs are discussed in terms of particle behavior in the surrounding region of the inlet of the sliding tribo-pairs.

KEY WORDS: chocolate, slurry lubrication, hard/soft surface pairing, particle suspensions, third body

1. Introduction

Chocolate is a unique food that exists as a solid at room temperature, yet melts and turns into a viscous fluid at the temperature of the human mouth [1]. This is due to the melting of the fat components of chocolate, which bind a variety of organic particles together [1]. The fats include cocoa butter and milk fat, and the particles include cocoa solids, sugar, and, in the case of milk chocolate, milk powder. Surfactants (e.g. lecithin) are also added to facilitate the homogenous dispersion of the hydrophilic solid components (e.g. sugar) with the hydrophobic fat components. Molten chocolate thus can be considered as slurry composed of a high concentration of various organic particles suspended in a continuous fat phase.

The rheological properties of chocolate are crucial in both the manufacturing and the consumption process in the human mouth, and thus have been extensively investigated [1–2]. As chocolate is a well-known example of a non-Newtonian fluid, a non-conventional approach, such as the Casson model [3–4], is required to describe its rheological properties. Recently, tribological characterization has also been employed to assess the properties of chocolate [5–6], since both hydrodynamic and boundary lubrication regime come into play and rheological measurements alone cannot com-

pletely describe the behavior of chocolate at a sliding interface.

Particle-containing lubrication systems are also of more general interest. The presence of particles in oil or grease has a significant impact on the performance of those fluids as lubricants. The particles can be wear debris generated during tribological process, soot from engines, or particles that have been added deliberately to improve lubrication. A variety of particles, including MoS_2 [7–16], graphite [14–19], fullerene [14], diamond [20], ceramics [15,21], and metals [15,22], have been added to lubricants to improve their properties. The effects vary enormously: Some studies report that particles improve anti-wear and lubricating performance [7–14,20], whereas others report a negligible or deleterious effect [15–19,21–22]. Many theoretical studies have also predicted both trends [23–29]. Clearly, the effect of particle addition on the lubricating properties of a fluid is strongly influenced by several parameters, such as the specific tribo-pair involved, the slide/roll ratio, the size, shape and chemical properties of the particles, the viscosity of the fluid, velocity, and load [7–29].

In this work, we have prepared a series of chocolate samples possessing various textural and compositional characteristics, in order to investigate their influence on rheological and tribological properties. As sliding interfaces, we have selected zirconia (ZrO_2) and poly(tetrafluoroethylene) (PTFE), representing both hard and soft counterfaces. These two materials have been used in all possible permutations, providing four combinations (pin material/disk material); (i) $\text{ZrO}_2/\text{ZrO}_2$

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(hard on hard), (ii) PTFE/ZrO₂ (soft on hard), (iii) ZrO₂/PTFE (hard on soft), and (iv) PTFE/PTFE (soft on soft).

The selection of tribo-pairs based upon hardness difference is motivated by an attempt to emulate the hard and soft components in the human mouth (teeth, tongue, and palate) and to better understand the tribological processes involved during chocolate consumption in the human mouth [6]. In addition, we note that the influence of the relative hardness of the tribo-pair and particles in the lubricant has been rarely investigated in the literature concerning slurry lubrication [7–29].

2. Experimental

2.1. Model chocolate samples

The components of the investigated chocolate samples are listed in table 1. The particle components include sugar (45 wt%), skim milk powder (18 wt%), and cocoa solids (5.4 wt%). The fat components include cocoa butter, milk fat, and lecithin and the contents are varied as shown below. In addition, vanillin is added as a minor component (0.025 wt%). Based upon the basic recipe in table 1, nineteen samples were produced by systematically varying the following parameters [6];

- (1) mean particle size; 21 and 52 μm
- (2) soya lecithin; 0.1 and 0.4 wt%
- (3) conching types (*conching is a process which blends the chocolate ingredients and leads to enhanced flavors* [1]); low shear/very long time (24 h), high shear/long time (6 h), and high shear/short time (2 h)
- (4) milk fat; 3.5, 5.75, and 8.0 wt%

The effect of replacing cocoa butter by milk fat and variation of the conching type was found to be insignificant for both the rheological and tribological properties. Thus, the chocolate samples are labeled based upon their particle size, **F** (Fine, 21 μm) or **C** (Coarse, 52 μm), and lecithin content, **1** (0.1 %) or **4** (0.4 %), only. The nineteen samples can be divided into four groups; **F1**, **C1**, **F4**, and **C4**. For each group, there are four or five samples with different values of milk fat content and conching type. A complete list of the chocolate samples with the varied parameters is presented in table 2.

2.2. Measurements of the rheological properties

The rheological characteristics of the chocolate samples were measured at 40 °C according to the International Office of Cocoa and Chocolate (IOCC) standard [1–2]. A Contraves (Zürich, Switzerland) Rheomat 115 apparatus with a DIN 125 cell was used. A Casson model was used to describe the viscosity [3–4]. The section of the experimental curves with positive slopes between 5 and 50 s⁻¹ was fitted with the Casson equation to estimate the plastic viscosity, η_{ca} , and the yield value, τ_{ca} .

2.3. Measurements of the lubrication properties

The lubrication properties of the chocolate samples between various tribo-pairs were characterized by means of a pin-on-disk tribometer (CSM, Neuchâtel, Switzerland). The entire set-up of the tribometer was housed in a plastic (PMMA) enclosure, which enabled the temperature and humidity of the experimental environment to be controlled. Before the start of the friction measurements, the chocolate samples were heated (40 ± 0.5 °C) inside the tribometer enclosure. The tribometer enclosure was kept at this temperature throughout the measurement. The molten chocolate samples were then transferred onto the disk prior to the formation of the contact between the weighted pin and disk. The friction forces were measured under a fixed applied load (10 N). The analog output voltage of the tribometer, corresponding to the friction force, was recorded with a Macintosh Power PC using LabView and an ADC card of the MIO family (both from National Instruments, Austin, TX, USA). The raw data consisted of friction force as a function of time. In cases where the dependence of the friction forces on the velocity was investigated, the velocity was varied from ~0.05 mm/s to a maximum of ~20 mm/s by changing the rotational rate at a fixed radius (6 mm).

2.4. Materials for the tribo-pairs

The materials used for the tribo-pairs in this work were ZrO₂ (Saphirwerk Industrieprodukte AG, Brügg, Switzerland) and PTFE (Maagtechnic, Dübendorf, Switzerland). These materials were used for both pin and disk, providing the combination of four tribo-pairs; (i) ZrO₂/ZrO₂ (ii) PTFE/ZrO₂ (iii) ZrO₂/PTFE, and

Table 1
The relative amounts (wt%) of common components in the chocolate samples.

Particle components				Fat components		Vanillin
Sugar 45%	Skim milk powder 18%	Cocoa solids 5.4%	Lecithin x% (= 0.1 or 0.4)	Milk fat y% (= 3.5, 5.75, or 8%)	Cocoa butter 31.7-x-y%	0.025%

Table 2
The list of the varied parameters of the chocolate samples; conching type, milk fat content, mean particle size, and lecithin content.

Sample number	Sample group notation	*Mean particle size	Lecithin content (%)	Conching type	Milk fat content (%)
1	F1	fine	0.1	low shear/24 h	3.5
2	F1	fine	0.1	low shear/24 h	5.75
3	F1	fine	0.1	high shear/6 h	5.75
4	F1	fine	0.1	high shear/6 h	5.75
5	C1	coarse	0.1	high shear/6 h	3.5
6	C1	coarse	0.1	low shear/24 h	5.75
7	C1	coarse	0.1	high shear/2 h	5.75
8	C1	coarse	0.1	high shear/2 h	8.0
9	C1	coarse	0.1	high shear/6 h	8.0
10	F4	fine	0.4	high shear/2 h	3.5
11	F4	fine	0.4	high shear/6 h	3.5
12	F4	fine	0.4	low shear/24 h	3.5
13	F4	fine	0.4	low shear/24 h	5.75
14	F4	fine	0.4	high shear/2 h	8.0
15	C4	coarse	0.4	high shear/2 h	3.5
16	C4	coarse	0.4	low shear/24 h	3.5
17	C4	coarse	0.4	high shear/2 h	5.75
18	C4	coarse	0.4	high shear/6 h	5.75
19	C4	coarse	0.4	low shear/24 h	8.0

* “fine” represents mean particle size of 21 μm and “coarse” represents mean particle size of 52 μm .

(iv) PTFE/PTFE. The radii of the spherical pins and disks were 3 and 30 mm, respectively. The ZrO_2 pin, ZrO_2 disk and PTFE pin were highly polished by the manufacturers and used as received without further treatment. The PTFE disks were polished prior to each measurement using sand paper (grade P500 > grade P1200 > grade PO).

3. Results

3.1. Rheological properties of the chocolate samples

As previously mentioned, the rheological properties of the model chocolate samples were characterized employing the Casson model [24,25]

$$\sqrt{\tau} = \sqrt{\tau_{\text{ca}}} + \sqrt{\eta_{\text{ca}}} \cdot \sqrt{D}$$

where τ is the shear stress, τ_{ca} is the Casson yield value, D is the shear rate, and η_{ca} is the Casson plastic viscosity. The yield value represents the shear stress required to break the structure of the chocolate and to initiate shear motion of the chocolate samples. The plastic viscosity represents the force necessary to maintain shear of the chocolates at high velocities [1,2]. In figure 1, the average values of τ_{ca} and η_{ca} for each chocolate sample group are plotted. The relative magnitudes of yield value and plastic viscosity are in the order of $\mathbf{F1} > \mathbf{F4} \geq \mathbf{C1} \geq \mathbf{C4}$ and $\mathbf{F1} > \mathbf{C1} \geq \mathbf{F4} \geq \mathbf{C4}$ respectively. $\mathbf{F1}$ is clearly distinguished from the other groups, while the distinction among the other groups is

not as clear. This observation implies that either increasing lecithin content from 0.1 to 0.4% or increasing mean particle size from 21 to 52 μm , thus effectively decreasing particle surface area, results in a significant reduction of both yield value and plastic viscosity. The Casson yield value and Casson plastic viscosity of the individual chocolate samples are listed in table 3.

3.2. Lubricating properties of the chocolate samples at the $\text{ZrO}_2/\text{ZrO}_2$ interface (hard on hard)

The frictional properties of the chocolate-lubricated $\text{ZrO}_2/\text{ZrO}_2$ tribo-pair were characterized by determining coefficients of friction ($\mu = dF/dN$, $N = 10 \text{ N}$) as a function of velocity within the range from ~ 0.05 to $\sim 2.0 \text{ mm/s}$. The sliding of the $\text{ZrO}_2/\text{ZrO}_2$ tribo-pair at higher velocities than $\sim 2.0 \text{ mm/s}$, whether dry or lubricated by the chocolate samples, was observed to exhibit a significant and irregular increase of the friction forces within the time scale of the measurement. The coefficients of friction of dry and fat-lubricated sliding have also been obtained for comparison. The results are plotted in figure 2. In this plot, the chocolate samples belonging to a certain group, $\mathbf{F1}$, $\mathbf{C1}$, $\mathbf{F4}$ or $\mathbf{C4}$, are designated by the same corresponding symbols. For clarity, error bars (typically $\sim \pm 0.005$ for μ) are not shown for all the plots below.

As shown in figure 2, the coefficients of friction, μ , for dry sliding were found to increase slightly with

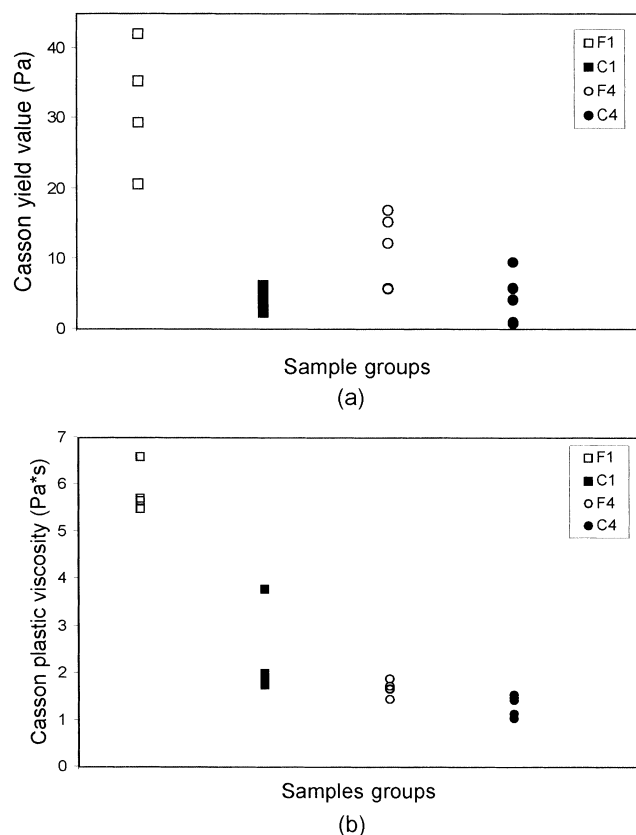


Figure 1. (a) The average Casson yield value, τ_{ca} , and (b) the average Casson plastic viscosity, η_{ca} , for the chocolate sample groups ($T = 40^\circ\text{C}$).

Table 3
Rheological properties of the chocolate samples.

Sample number	Sample group notation	Casson plastic viscosity (Pa s)	Casson yield value (Pa)
1	F1	6.59	29.36
2	F1	5.7	20.62
3	F1	5.66	35.32
4	F1	5.48	42.08
5	C1	1.75	3.86
6	C1	3.79	6.11
7	C1	1.98	4.85
8	C1	1.92	5.15
9	C1	1.77	2.3
10	F4	1.73	16.86
11	F4	1.44	12.2
12	F4	1.66	5.68
13	F4	1.88	5.71
14	F4	1.64	15.2
15	C4	1.12	9.41
16	C4	1.54	0.87
17	C4	1.42	4.09
18	C4	1.03	5.73
19	C4	1.48	0.71

increasing velocity (from 0.187 to 0.234). Lubrication by the fat components alone exhibited reduced and virtually constant μ values within the same range of the velocity; 0.100 ± 0.001 by milk fat and 0.084 ± 0.003 by cocoa butter. The $\text{ZrO}_2/\text{ZrO}_2$ tribo-pair exhibited further reduction of μ when it was lubricated by the molten chocolate samples. The μ was found to exhibit different velocity dependence for the chocolate samples having different textural/compositional features. For **F1** and **C1**, μ decreased with increasing velocity (from 0.074 to 0.059 on average for **F1** and from 0.061 to 0.051 on average for **C1**), while for **F4** and **C4**, μ increased with increasing velocity (from 0.042 to 0.048 on average for **F4** and from 0.037 to 0.050 on average for **C4**). The differences between different sample groups are higher at low velocities. The order of μ is **F1** \geq **C1** \geq **F4** \geq **C4**. The differences disappear at high velocities. It is noted that neither velocity dependence nor lubricant texture/composition dependence are particularly pronounced in the chocolate-lubricated sliding of $\text{ZrO}_2/\text{ZrO}_2$.

Among the four tribo-pairs employed in this work, $\text{ZrO}_2/\text{ZrO}_2$ was observed to be the only tribo-pair for which the chocolate samples show lower friction forces than the pure fat components. Furthermore, comparing the same chocolate sample as a lubricant over all pairs, $\text{ZrO}_2/\text{ZrO}_2$ showed the lowest coefficient of friction. In other words, the presence of the particles in the chocolate samples appears to contribute to lower friction in the lubrication of $\text{ZrO}_2/\text{ZrO}_2$ interface.

3.3. Lubrication properties of the chocolate samples at the PTFE/ ZrO_2 interface (soft on hard)

As the chocolate-lubricated sliding of PTFE/ ZrO_2 pair exhibited stable and reproducible frictional behavior, even at velocities higher than ~ 2.0 mm/s, the range was extended from ~ 0.05 to ~ 20 mm/s, as shown in figure 3.

The dry sliding showed a gradual increase of the coefficient of friction with increasing velocity (from 0.012 to 0.049). The lubrication by the fat components led to fairly constant friction over the same velocity range; $\mu = 0.015 \pm 0.003$ by milk fat and 0.019 ± 0.002 by cocoa butter. Thus, the fat components appeared to reduce the friction slightly at high velocities. Chocolate lubrication, however, exhibited significantly higher μ values within the measured velocity range. The magnitude of the increase was shown to be strongly dependent on the velocity and textural/compositional features. The μ decreased with increasing velocity for **F1**, **C1**, and **F4** (from 0.151 to 0.082 on average for **F1**, from 0.131 to 0.072 on average for **C1**, and from 0.092 to 0.077 for **F4**), while it increased with increasing velocity for **C4** (from 0.052 to 0.076 on average). The μ values for different chocolate sample groups are quite distinct at low velocities and were in the order of

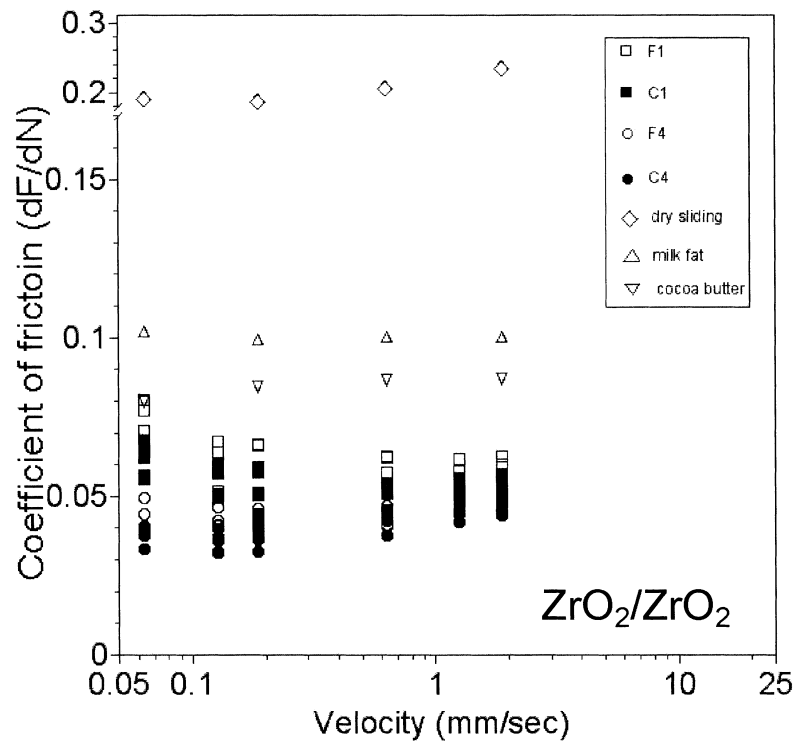


Figure 2. The coefficients of friction versus velocity plots of dry, the fat, and the chocolate-lubricated sliding of $\text{ZrO}_2/\text{ZrO}_2$ tribo-pair ($T = 40^\circ\text{C}$, load = 10 N).

F1 > C1 > F4 > C4. As in the case of $\text{ZrO}_2/\text{ZrO}_2$, this difference disappeared at higher velocities. Surface analysis of the ZrO_2 disk following the fat- or chocolate-lubricated sliding using X-ray photoelectron spectroscopy (XPS) showed no evidence for PTFE transfer.

The lubricating effect of the chocolate sample groups and the resulting velocity-dependent frictional behavior was similar for both $\text{ZrO}_2/\text{ZrO}_2$ and PTFE/ZrO_2 tribo-pairs; (i) the coefficients of friction are in the same order of **F1**, **C1**, **F4** and **C4** (ii) the difference in the coefficient of friction is more pronounced at low velocities (iii) the velocity-dependent frictional behavior shifts from a decreasing to an increasing trend in the order **F1**, **C1**, **F4**, **C4**. Nevertheless, replacement of the one hard counterface (ZrO_2) by a soft counterface (PTFE) led to several differences; (i) the $\text{ZrO}_2/\text{ZrO}_2$ pair exhibited lower μ values when lubricated by the chocolate samples than by the fats, while the PTFE/ZrO_2 pair exhibited higher μ values when lubricated by the chocolate samples than the fats (ii) PTFE/ZrO_2 always displayed higher μ values than $\text{ZrO}_2/\text{ZrO}_2$ for the same chocolate sample (see figures 2 and 3); the difference is systematically correlated with the textural/compositional parameters of the chocolate samples and is highest when **F1** is employed as a lubricant, followed by **C1** and **F4**, and **C4** (iii) PTFE/ZrO_2 exhibited a more pronounced velocity dependence than $\text{ZrO}_2/\text{ZrO}_2$. Furthermore, the distinction between the groups of chocolate samples

at low velocities is clearer when the chocolate samples lubricate the PTFE/ZrO_2 tribo-pair than $\text{ZrO}_2/\text{ZrO}_2$.

3.4. Lubrication properties of the chocolate samples at the ZrO_2/PTFE interface (hard on soft)

The ZrO_2/PTFE interface is an inversion of the PTFE/ZrO_2 interface, for which one might expect similar tribological properties. However, with pin-on-disk geometry, the chocolate-lubricated ZrO_2/PTFE has been observed to exhibit significantly different behavior from that of PTFE/ZrO_2 . Figure 4 shows the recorded friction versus time data of PTFE/ZrO_2 and ZrO_2/PTFE lubricated by **C4** (sample number 17 in table 1, velocity at 0.188 mm/s). In this plot, the x -axis represents the time scale and thus shows the repeated contact position along the track (5 rotations). When the measurement was performed in the absence of the chocolate samples, whether dry or fat-lubricated, ZrO_2/PTFE exhibited slightly higher friction forces, yet no other specific difference was observed. When the tribo-pairs were lubricated by the chocolate samples, a series of spikes in the friction signal was observed for ZrO_2/PTFE , but not for PTFE/ZrO_2 (figure 4). Controlled measurements of ZrO_2/PTFE from various starting positions revealed that the positions of the spikes corresponds to the initial loading

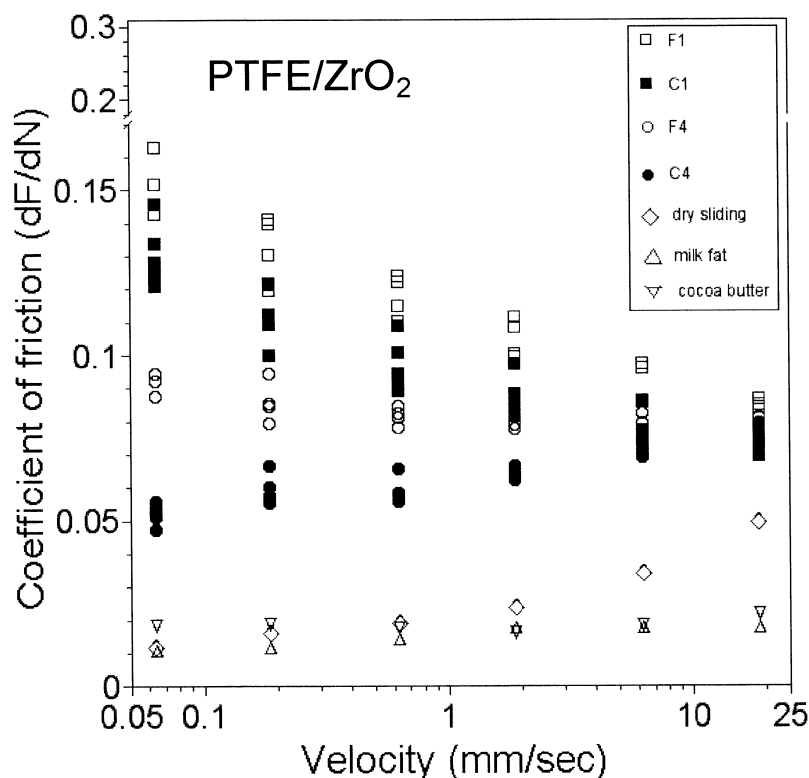


Figure 3. The coefficients of friction versus velocity plots of dry, the fat, and the chocolate-lubricated sliding of PTFE/ZrO₂ tribo-pair ($T = 40^{\circ}\text{C}$, load = 10 N).

point of the weighted pin-on-disk, and the frequency of the spikes corresponds to the rotational frequency of the disk.

The occurrence of these spikes is influenced by the textural/compositional parameters of the chocolate samples. In figure 5, representative raw data of friction forces-versus-time plots for each group of samples measured under a fixed velocity (0.188 mm/s) are presented. In the case of **C4** (sample number 14 in table 2), the spiky friction force signal is observed at the loading points only (figure 5(d)). Repeated measurements up to a maximum of 500 rotations showed that this behavior persists within these cycles. In the case of **F1** (sample number 1 in table 2), the friction spikes rapidly develop even in regions outside the initial loading point (figure 5(a)). The other cases, **C1** (sample number 5 in table 2) and **F4** (sample number 10 in table 2), show a behavior between these two extremes (figure 5(b) and (c)).

The coefficients of friction for chocolate-lubricated sliding as well as dry and fat-lubricated sliding of ZrO₂/PTFE were obtained by averaging the friction signals, including spikes, over 10 rotations under a fixed velocity (0.188 mm/s). The results are presented in figure 6. The μ of dry and fat-lubricated sliding of ZrO₂/PTFE has been measured to be 0.070 (dry), 0.060 (milk fat), and 0.058 (cocoa butter) respectively. As in the case of PTFE/ZrO₂, the μ of chocolate-lubricated ZrO₂/

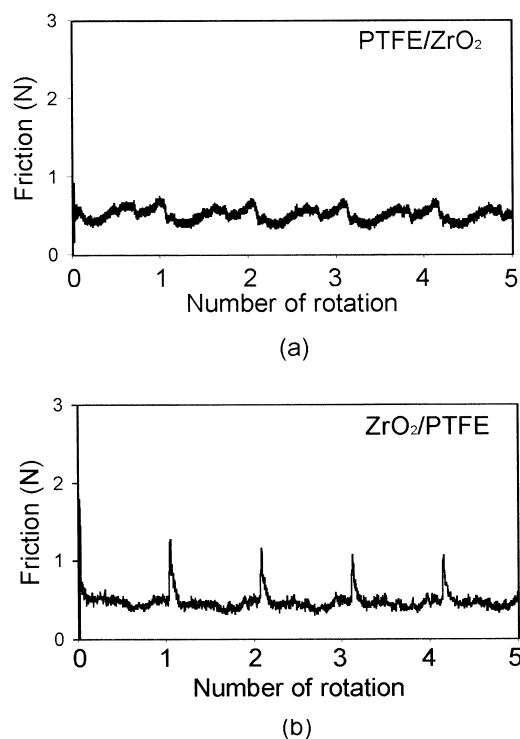


Figure 4. The friction forces of the chocolate-lubricated (**C4**, sample number 17 in table 2) sliding of (a) PTFE/ZrO₂ and (b) ZrO₂/PTFE tribo-pairs as a function of time (or the number of rotation) ($T = 40^{\circ}\text{C}$, load = 10 N, velocity = 0.188 mm/s).

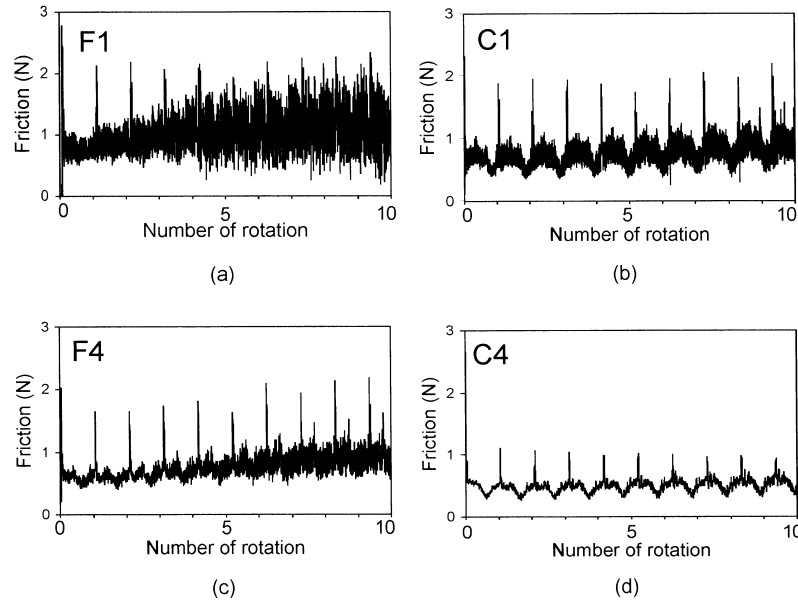


Figure 5. The friction forces of ZrO_2/PTFE tribo-pair lubricated by four different chocolate samples as a function of time (or the number of rotation) (a) **F1** (sample number 1 in table 2) (b) **C1** (sample number 5 in table 2) (c) **F4** (sample number 10 in table 2) and (d) **C4** (sample number 14 in table 2) ($T = 40^\circ\text{C}$, load = 10 N, velocity = 0.188 mm/s).

PTFE was measured to be in the order of **F1** (0.132 ± 0.023) > **C1** (0.109 ± 0.031) > **F4** (0.067 ± 0.008) > **C4** (0.051 ± 0.003).

3.5. Lubrication properties of the chocolate samples at PTFE/PTFE (soft on soft)

Finally, the frictional properties of chocolate-lubricated PTFE/PTFE have been characterized by acquiring coefficients of friction as a function of velocity. As in the

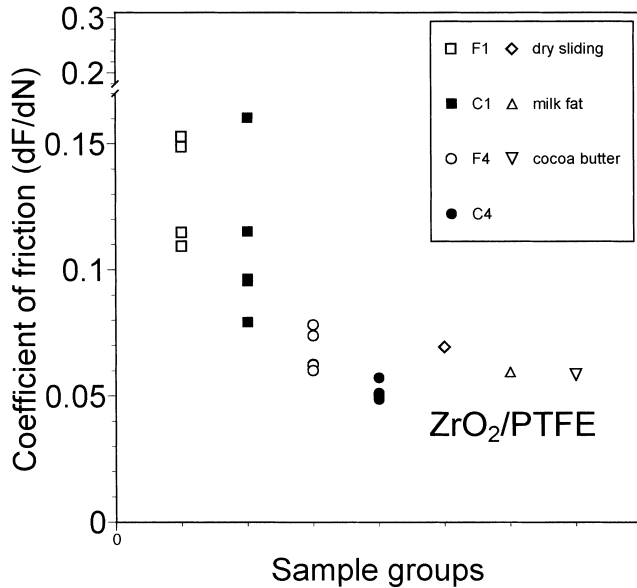


Figure 6. The coefficients of friction of dry, the fat, and the chocolate-lubricated sliding of ZrO_2/PTFE tribo-pair ($T = 40^\circ\text{C}$, load = 10 N, velocity = 0.188 mm/s).

case of $\text{ZrO}_2/\text{ZrO}_2$, the chocolate-lubricated sliding of PTFE/PTFE also exhibited a rapid increase of friction forces at high velocities ($> 2 \text{ mm/s}$), thus the range was selected from ~ 0.05 to 2.0 mm/s . The data are shown in figure 7.

The μ of dry PTFE/PTFE was found to increase slightly with increasing velocity; from 0.036 to 0.049. In contrast to the dry case, the μ of fat-lubricated PTFE/PTFE was found to decrease slightly with increasing velocity; from 0.040 to 0.034 by milk fat and from 0.036 to 0.030 by cocoa butter). Thus, the fat components appeared to reduce the friction of PTFE/PTFE mainly at high velocities. As in the case of PTFE/ ZrO_2 and ZrO_2/PTFE , the lubrication of PTFE/PTFE with chocolate samples resulted in a significant increase of the coefficients of friction compared with dry sliding or fat lubrication. For all chocolate sample groups, the μ values were virtually constant as a function of velocity and in the order of **C1** (0.126 ± 0.007) \approx **C4** (0.119 ± 0.009) \geq **F1** (0.106 ± 0.007) \approx **F4** (0.102 ± 0.005). In contrast to previous cases, where the friction is roughly in the decreasing order **F1**, **C1**, **F4** and **C4**, the chocolate-lubricated PTFE/PTFE is dominated by the effects of particle size in the chocolate samples. It is also noted that the chocolate-lubricated PTFE/PTFE exhibited none of the spiky frictional features that were observed with ZrO_2/PTFE although the same soft track material was employed.

4. Discussion

4.1. General consideration

As mentioned in the Introduction, the choice of the materials for the tribo-pair in this work was motivated

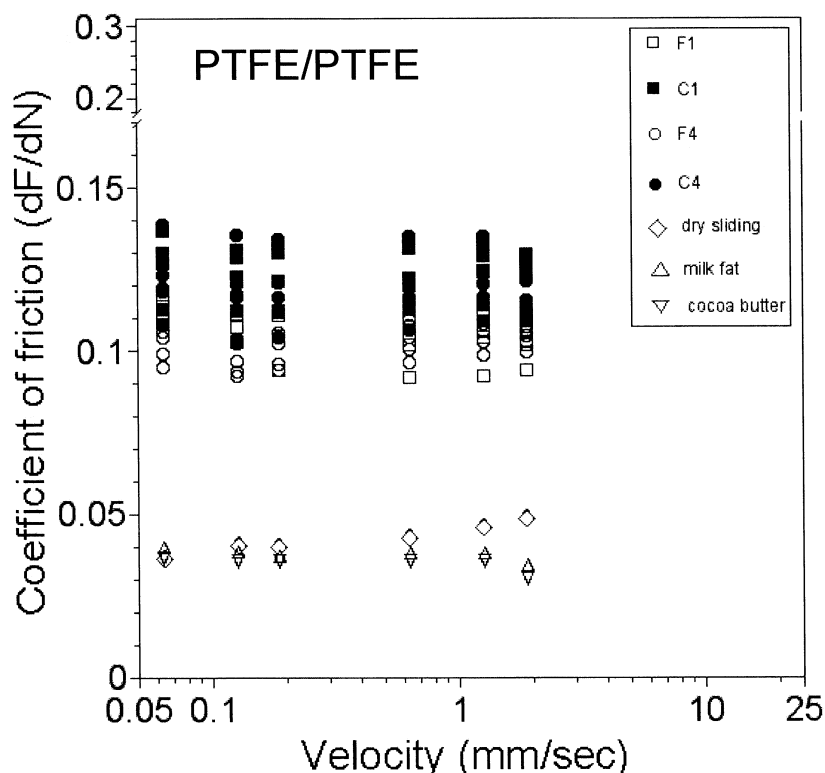


Figure 7. The coefficients of friction versus velocity plots of dry, the fat, and the chocolate-lubricated sliding of PTFE/PTFE tribo-pair ($T = 40^{\circ}\text{C}$, load = 10 N).

by the hardness difference; ZrO_2 represents a hard material (Vickers Hardness 1200 Hv [30]) while PTFE represents a soft material (Vickers hardness 32 Hv [31]). The un-lubricated sliding of these materials at various combinations revealed that they possess significantly different frictional properties. As shown in figure 2, the $\text{ZrO}_2/\text{ZrO}_2$ exhibits high μ values, ~ 0.2 , while the cases involving PTFE showed significantly lower μ values, ~ 0.05 or less. The lower friction of the tribo-pair involving PTFE is attributed to better lubricating properties of PTFE itself [32,33]. For this reason, negligible significant friction reduction is observed for tribo-pairs involving PTFE, while a considerable friction reduction is observed for $\text{ZrO}_2/\text{ZrO}_2$ when it is lubricated by the fat components.

The primary difference of the model chocolate samples compared with the fat components as lubricants is that the chocolate samples contain a high concentration of particles suspended in a continuous fat phase (~ 70 wt% in this work). The presence of the particles in the fat phase causes two major changes in lubricant properties; (1) the viscosity of the fluid generally increases and (2) the tribo-pairs are subjected to abrasive wear. Typical kinematic viscosity of the vegetable oils is less than 50 cSt ($1\text{cSt} = 10^{-6}\text{m}^2\text{s}^{-1}$ and the density is around 1 g/ml at 40°C [34]. Thus, the dynamic viscosity of the fat components can be estimated as $\sim 5 \times 10^{-2}\text{Pa}\cdot\text{s}$. As the viscosity of the chocolate samples has serious non-Newtonian characteristics, it is not strictly valid to

directly compare it with that of the pure fat components. If we ignore the non-Newtonian rheological characteristics of the chocolate samples, however, the chocolate samples appear to be roughly two orders of magnitude more viscous than the pure fat components (see table 3). It is only for the $\text{ZrO}_2/\text{ZrO}_2$ tribo-pair, however, that the chocolate samples provide lower friction forces than the pure fats. Clearly, this is related to particle embedment and abrasive wear in the PTFE-containing systems.

In general, if the hardness of an abrasive particle (sphere) is 1.25 times higher than that of the plane ($H_a/H_s > 1.25$ where H_a and H_s are the hardness of abrasive particle and plane respectively), it is expected that the particle indents the plane and *vice versa* [35]. Although the Vickers hardness of the organic particles in the chocolate samples is not well characterized, that of crystalline sucrose, which is the major component of the sugar, is known to be 755 Hv [36]. This value is close to the lower limit of the hardness of silica particles [35]. Thus, the crystalline sucrose particles are sufficiently hard to deform PTFE and sufficiently soft to be deformed by ZrO_2 . Assuming that the actual Vickers hardness of the hardest particles in the chocolate samples is comparable to that of pure sucrose crystals, plastic indentation and abrasive wear by the particles in the chocolate sample is expected to occur exclusively toward PTFE. This accounts for the higher friction forces of the chocolate samples compared with the fat components for the tribo-pairs involving PTFE.

The mechanism of the abrasive wear when particles are supplied via a continuous medium, e.g., a slurry, requires further consideration. Previous optical interferometry studies for a particle/oil system have shown that for the sliding contact in a sphere-on-plane configuration, lubrication by a slurry leads to an accumulation of particles at the inlet [15–17]. According to these studies, a portion of the accumulated particles was observed to be swept around the track, sometimes blocking the supply of oil into the contact area, while another fraction was observed to bypass the contact area. The particle accumulation at the inlet, however, does not completely exclude the possibility of a few particles passing through the contact area. The number of particles that can pass through the sliding contact, although significantly smaller than in the case of rolling contact [15–17], was observed to depend upon particle type, size, velocity and load. Theoretical studies have also led to a similar conclusion [27–29]. It should be emphasized that the hardness of the tribo-pair components would also play an important role in determining this behavior, although not much attention has been paid to this effect. Although optical interferometry allows the investigation of particle behavior in real space by providing images, the choice of disks for this method is limited to transparent materials and is thus not applicable to the materials in this study. Nevertheless, we believe that the particle behavior in the surrounding region of the inlet, including accumulation, sweeping around, bypass, and entrainment, is generally applicable to all slurry-lubricated contacts.

4.2. Influence of the hardness of the tribo-pair on the lubrication properties of the chocolate samples

As described in the previous section, the lubrication properties of the fluids containing particles are significantly influenced by the particle behavior at the perimeter of the contact area. This behavior is expected to be further influenced by the hardness of the tribo-pair, and we have systematically varied the configuration of the ZrO_2 and PTFE tribo-pair in this work. For $\text{ZrO}_2/\text{ZrO}_2$, both surfaces are composed of harder material than the particles. Thus, this tribo-pair is considered to be free from abrasive wear by the particles in the chocolate samples. In fact, no evidence for the wear was observed on this tribo-pair when examined by optical microscopy. The lower friction forces observed for the chocolate samples compared with the fat components suggests that some particles are being entrained and passing through the contact area, consequently contributing to the formation of a better lubricant film than obtainable with the pure fat components. Several other possible modes of particle behavior, including accumulation at the inlet, sweeping around the sliding track, and starvation of the fat supply into the contact area, would cause higher or at least equivalent frictional forces. The entrainment of the particles into the contact area can cause abrasive wear and higher friction forces [27–29]. In the case of $\text{ZrO}_2/\text{ZrO}_2$, however, the influence of this effect seems negligible due to higher hardness of the surfaces. A schematic illustration for this mechanism is shown in figure 8(a).

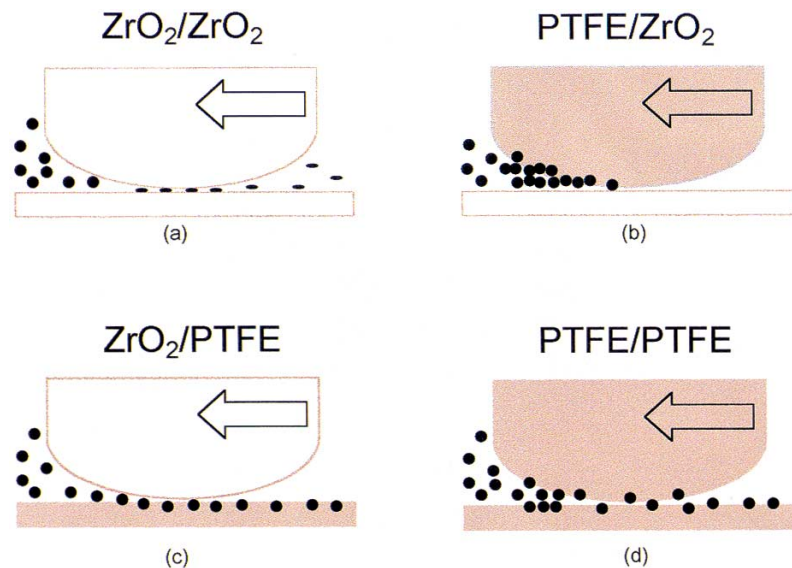


Figure 8. A schematic model of the particle behavior at the vicinity and contact area of the tribo-pairs (a) $\text{ZrO}_2/\text{ZrO}_2$; particles are deformed as they pass through contact area (b) PTFE/ZrO_2 ; particles accumulate at inlet and become embedded in pin (c) ZrO_2/PTFE ; particles become embedded in disk as they pass through contact area (d) PTFE/PTFE ; particles become embedded in both pin and disk as they pass through contact area. The particles are dispersed in a continuous fat phase (not shown).

For PTFE/ZrO₂, plastic indentation and abrasive wear is likely to occur only on the PTFE pin. This may increase the possibility of accumulating the particles at the sliding inlet as shown in figure 8(b). Thus, the accumulated particles are dragged around the ZrO₂ disk and generate additional friction forces. This could account for the higher friction forces compared with ZrO₂/ZrO₂ case when the same chocolate sample is used as a lubricant. Due to the much higher hardness of the particles than the slider (PTFE), it is less likely that the particles can be entrained into and pass through the contact area than in the ZrO₂/ZrO₂ case.

For ZrO₂/PTFE, the same mechanism in PTFE/ZrO₂ case must be occurring. However, different particle behavior is also expected for a different contact configuration. As the soft part (PTFE) comprises the track and the hard part (ZrO₂) slides over it, the particles at the inlet are more likely to be embedded than sweep around the track. In other words, the sliding of the hard slider (ZrO₂) induces the embedding of the particles as well as passing over the embedded particles, as illustrated in figure 8(c). This behavior contrasts with the ZrO₂/ZrO₂ case, where the accumulated particles are deformed and contrasts with the PTFE/ZrO₂ case where the accumulated particles are dragged around the track.

For PTFE/PTFE, the particles are likely to be embedded in both pin and disk and the most serious abrasive wear would be expected. As the hardness of the slider and the track are equivalent, the accumulated particles at the inlet may be dragged around the track by the sliding as well as being embedded into the track, both of which contribute to friction forces (figure 8(d)). The generally higher friction forces obtained from PTFE/PTFE compared with the other tribo-pairs are consistent with this assumption.

4.3. Influence of the textural/compositional features on the rheological and lubrication properties of the chocolate samples

As is well known, the role of the surfactant (lecithin) in chocolate is to facilitate the homogeneous mixture of the hydrophilic particle components (e.g. sugar) with continuous fat phase and thus effectively reduce the viscosity [1]. However, if too much lecithin is added, normally more than 0.5 wt%, the viscosity of chocolate increases, due to formation of micelles or bi-layers around the sugar by the excess lecithin [1]. This accounts for a distinctively reduced Casson yield value and Casson plastic viscosity of **C1** and **F4** compared with **F1**, while those of **C4** are not further reduced. In other words, either increasing the particle size from 25 to 51 μm on average or increasing the lecithin content from 0.1 to 0.4% results in a similar effect in reducing viscosity. The various rheological properties of the

chocolate samples are thus believed to have resulted from the interplay of the particle size (and thus the surface area of the particles) and the lecithin content.

For the tribo-pairs involving ZrO₂(ZrO₂/ZrO₂, PTFE/ZrO₂, and ZrO₂/PTFE), the lubricating properties of the chocolate samples have been also observed in the order of **F1** (highest friction), **C1**, **F4** and **C4** (lowest friction) and the distinction between different groups is clearer for lower velocities. For PTFE/PTFE, however, the μ values of **C1** and **C4** have been observed to be slightly higher than **F1** and **F4**. In other words, the rheological properties of the chocolate samples are closely associated with their lubricating properties for the tribo-pairs involving ZrO₂, while not for the tribo-pair composed of PTFE alone. For oil-based lubricants that are free from particles, the role of the rheological properties of a lubricant is normally discussed in terms of their performance to form a film at the contact area. For slurry lubricants, however, the lubricating properties need to be described in terms of particle behavior both in the contact area and also in the surrounding region.

As mentioned above, slurry-lubricated sliding allows some portions of the particles to accumulate at the entrainment edge, while some others are pushed away from the inlet and bypass the contact area. The subsequent behavior of the accumulated particles is strongly dependent upon the relative hardness of the tribo-pair/particles, as schematically illustrated in figure 8. The number of accumulated particle is, however, thought to be closely associated with the rheological properties of the chocolate samples. In cases where the particle size is identical, yet rheological properties are clearly different, e.g., **F1** versus **F4**, the particles in a less-viscous fluid (**F4**) possess higher mobility than those in more viscous fluid (**F1**). Consequently, they are more easily pushed away when subjected to shear interaction with the tribo-pair. This is most clearly manifested for the lubrication of ZrO₂/PTFE, in which the highly viscous lubricants (**F1**) generate the spiky friction signals, even outside the initial loading point (see figure 4(a)), while the least viscous lubricants limit such behavior to the loading point (**C4**) (figure 4(d)). As the embedding of the particles on the soft track, which is responsible for the spiky friction signals, is preceded by particle accumulation at the inlet, the absence of the spiky friction signals outside the loading point for **C4** also suggests the absence of particle accumulation as well. Although the detailed particle behavior after accumulation may be different for the other tribo-pairs, the same mechanism is believed to be mainly responsible for the higher friction forces for the more viscous chocolate samples. This must be applicable to even for PTFE/PTFE. However, the abrasive wear mechanism dominates the rheological properties of the fluid due to softness of both surfaces.

5. Conclusions

We have revealed the rheological and lubrication properties of a series of model chocolate samples with systematically different textural/compositional features. Four permutations of a hard (ZrO_2) and a soft (PTFE) material have been realized for the tribo-pairs; $\text{ZrO}_2/\text{ZrO}_2$, PTFE/ ZrO_2 , ZrO_2 /PTFE, and PTFE/PTFE. Particle size and surfactant (lecithin) content were observed to significantly influence the rheological properties; either increasing the lecithin content (from 0.1 to 0.4 wt%) or increasing the mean particle size (from 21 to 52 μm) reduced both the Casson yield value, τ_{ca} , and the Casson plastic viscosity, η_{ca} . The lubrication properties of the chocolate samples were also observed to be dependent upon the textural/compositional characteristics of the chocolate samples, and further influenced by the choice of the tribo-pairs. For $\text{ZrO}_2/\text{ZrO}_2$, the chocolate samples showed lower friction forces, while the other tribo-pairs involving PTFE (PTFE/ ZrO_2 , ZrO_2 /PTFE, and PTFE/PTFE) showed higher friction forces compared with the particle-free fat components. The difference is understood in terms of the relative hardness of the particles and the tribo-pair, influencing particle behavior at the surrounding region of the sliding contact. It seems that these results indicate that the relative hardness of the particles with respect to tribo-pair should be considered in the case of slurry-lubricated contacts, in order to fully account for tribological phenomena.

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